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â€¢ A nonlinear system can oscillate with frequencies which are submultiples or multiples of ... ii) >0 is an unstable focus iii) $= 0$ is a center. 18. 1. Introduction to Nonlinear Systems Other cases a)

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have chosen to

Design For Nonlinear Control Systems

where $f(x)$ is an $m \times m$ matrix of smooth functions of x , defined and invertible for all $x \in \mathbb{R}^n$. Note that feedback transformations of this kind, which actually correspond to x -dependent changes of coordinates in the space of input values, have been encountered several times before in the design of nonlinear control systems.

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Emilio Frazzoli, 16.30/31 Feedback Control Systems, Overview of Nonlinear Control Synthesis, Aeronautics and Astronautics, MIT, 2010 J. Tani (ETH) Lecture 12: Control Systems II 25/05/2018 20 / 40 Gain Scheduling 2

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